

Introduction - Units and Dimensions - Laws of Mechanics - Lame's theorem, Parallelogram and triangular Law of forces - Vectors - Vectorial representation of forces and moments - Vector operations: additions, subtraction, dot product, cross product - Coplanar Forces - Resolution and Composition of forces - Equilibrium of a particle - Equilibrium of a particle in three dimensions - Equivalent systems of forces - Principle of transmissibility - Single equivalent force.

| Unit II | EQUILIBRIUM OF RIGID BODIES | $\mathbf{6}$ | 3 | $\mathbf{0}$ | $\mathbf{9}$ |
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Free body diagram - Types of supports and their reactions - requirements of stable equilibrium - Moments and Couples Moment of a force about a point and about an axis - Vectorial representation of moments and couples - Scalar components of a moment - Varignon's theorem - Equilibrium of Rigid bodies in two dimensions - Equilibrium of Rigid bodies in three dimensions.

| Unit III | PROPERTIES OF SURFACES AND FRICTION | 6 | 3 | 0 | 9 |
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Centroids and centre of mass- Centroids of lines and areas-Rectangular, Circular, triangular areas by integration-T section, I section .-Angle Section, Hollow section by using standard formula Theorems of pappus Area moments of inertia of plane areas-Rectangular, circular, triangular areas by integration-T section, I section, Angle section, Hollow section by using standard formula parallel Axis Theorem and perpendicular Axis Theorem-Principal Moments of Inertia of plane areas Mass moment of inertia.

| Unit IV | KINEMATICS AND KINETICS OF PARTICLES | 6 | 3 | 0 | 9 |
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| Displacement, Velocity and acceleration, their relationship-Relative motion-Newton's low of motion -Work Energy Equation-Impulse and Momentum-Impact of elastic bodies |  |  |  |  |  |
| Unit V | KINEMATICS AND KINETICS OF RIGID BODIES | 6 | 3 | 0 | 9 |
| Plane motion- Absolute motion - Relative motion - Translating ares and Rolling Axes- Work and Energy Impulse and Momentum |  |  |  |  |  |

Total= 45 Periods

| Text Books: |  |
| :--- | :--- | :--- |
| 1 | Rajasekaran S and Sankara subramanian G., Fundamentals of Engineering Mechanics, Vikas Publishing <br> House Pvt. Ltd., 3rd Edition,2017. |
| 2 | Bansal R.K., Engineering Mechanics, Laxmi Publications (P) Ltd., 8th Edition, 2015. |
| 3 | Palanichamy M.S. and Nagan S, Engineering Mechanics, Laxmi Publication(P) Ltd.,2022 |
| Reference Books: |  |
| 1 | Kumar K.L., Engineering Mechanic, Tata McGraw-Hill Publishing Company Limited, New Delhi, 4th Edition, 2017. |

2 Beer F.P and Johnson Jr. E.R. Vector Mechanics for Engineers, Vol. 1 Statics and Vol. 2 Dynamics, McGraw-Hill International Edition, 12th Edition, 2019

3 Hibbeller R.C., Engineering Mechanics, Vol. 1 Statics, Vol. 2 Dynamics, Pearson Education Asia Pvt. Ltd., 14th Edition, 2017.

Irving H. Shames, Engineering Mechanics - Statics and Dynamics, IV Edition - Pearson Education Asia Pvt. Ltd., 4th Edition, 2005.

| Course Outcomes: |  | Bloom's <br> Taxonomy <br> Mapped |
| :--- | :--- | :---: |
| CO1 | Demonstrate the basics and statics of the particle by applying, knowledge of mathematics and <br> engineering sciences | Apply |
| $\mathbf{C O 2}$ | Explain the equilibrium of rigid bodies and draw the free body diagram and mention the <br> supports and the reaction for the diagram. | Apply |
| $\mathbf{C O 3}$ | Select and apply appropriate techniques to determine the areas of the surfaces using the various <br> theorems and find the moment of inertia of different body shapes | Apply |
| $\mathbf{C O 4}$ | Understand the complex engineering problems to solve the dynamics of particles | Apply |
| $\mathbf{C O 5}$ | Understand the mechanisms of rigid bodies using Civil engineering solutions for sustainable <br> development. | Apply |

## COURSE ARTICULATION MATRIX

| COs |  |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
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| POs | PO1 | PO2 | PO3 | PO4 | PO5 | PO6 | PO7 | PO8 | PO9 | PO10 | PO11 | PO12 | PSO1 | PSO2 | PSO3 |
| CO1 | 2 | 3 | 1 | 1 | - | - | 1 | - | - | - | - | - | 1 | - | - |
| CO2 | 2 | 3 | 2 | 1 | - | - | 1 | - | - | - | - | - | 1 | - | - |
| CO3 | 2 | 3 | 2 | 1 | - | - | 1 | - | - | - | - | - | 1 | - | - |
| CO4 | 2 | 3 | 2 | 1 | - | - | 1 | - | - | - | - | - | 1 | - | - |
| CO5 | 2 | 3 | 2 | 1 | - | - | 1 | - | - | - | - | - | 1 | - | - |
| Avg | 2 | 3 | 1.8 | 1 | - | - | 1 | - | - | - | - | - | 1 | - | - |

