	22EEOE02 INDUSTRIAL DRIVES						VI
Pow	REQUISIT	OE	OE Credit		3		
Powe							TH
Power Electronics, and Electrical Machines Hours\Week						0	3
Cou	rse Objective	s:					
1.	To understan	d the basic components of electric drive system,					
2.	To analyze th	e operation and performance of the chopper fed DC d	rive,				
3.	To understan	d the operation and performance of AC motor drives					
4.	To understand	d the advanced techniques in the control of industrial	drives.				
Unit	I BA		9	0	0	9	
Elect	ric drive - ir	troduction and advantages, types and choice of elec	ctric drive, compo	onents	of el	ectric	drive
		uty class classification continuous, short time	and intermitter	nt dut	y, sp	peed-t	orque
		DC and Induction motor drive.				_	
Unit		C DRIVES		9	0	0	9
		oper and duty ratio control, chopper fed dc motor for					
		e, armature current waveform and ripple, calculation	on of losses in d	le mote	or an	d cho	opper,
		ive, smooth starting,					
		ing and generating modes operation of a separate					
		achine; single-quadrant, two-quadrant and four-quad	lrant choppers; st	eady-st	ate o	perati	ion of
		opper fed dc drive, regenerative braking		0		0	
Unit		C DRIVES	<u>,</u>	9	0	0	9
		on motor equivalent circuit and torque-speed charac					
		ge, applied frequency and applied voltage and frequerating point, constant flux operation, flux weakenin		ue-spe	ea cu	rves	of far
		ONTROL OF DC AND AC DRIVES	ig operation.	9	0	0	9
			U U	U	19		
Unit			n dynamic mode	$\frac{1}{1}$ of de	mot	or du	nomic
Unit Cont		of DC drive, inner current loop and outer speed loop					
Unit Cont equa	tions and trar	of DC drive, inner current loop and outer speed loop asfer functions, modeling of chopper as gain with swi	itching delay, plai	nt trans	fer fi	unctic	
Unit Cont equa contr	tions and trar oller design,	of DC drive, inner current loop and outer speed loo sfer functions, modeling of chopper as gain with swi current controller specification and design, speed cont	itching delay, plan troller specification	nt trans	fer fu lesig	unction.	on, foi
Unit Cont equa contr Gene	tions and trar coller design, cration of thre	of DC drive, inner current loop and outer speed loop isfer functions, modeling of chopper as gain with swi current controller specification and design, speed con- e-phase PWM signals, sinusoidal modulation, space	itching delay, plan troller specification vector theory, con	nt trans on and onventio	fer fu desig nal sj	unctic n. pace v	on, foi vector
Unit Cont equa contr Gene mod	tions and trar coller design, eration of thre ulation; const	of DC drive, inner current loop and outer speed loop isfer functions, modeling of chopper as gain with swi current controller specification and design, speed cont e-phase PWM signals, sinusoidal modulation, space ant V/f control of induction motor. Operation of slip-	itching delay, plan troller specification vector theory, con- ring induction mo-	nt trans on and onventio otor wi	fer fu design nal sj th ex	unctic n. pace v	on, for vector
Unit Cont equa contr Gene modu resis	tions and tran oller design, eration of three ulation; const tance, power	of DC drive, inner current loop and outer speed loo asfer functions, modeling of chopper as gain with swi current controller specification and design, speed cont e-phase PWM signals, sinusoidal modulation, space ant V/f control of induction motor. Operation of slip- electronic based rotor side control of slip ring motor, s	itching delay, plan troller specification vector theory, con- ring induction mo-	nt trans on and onventio otor wi	fer fu design nal sj th ex	unctic n. pace v	on, foi vector
Unit Cont equa contr Gene modu resis Unit	tions and tran coller design, cration of three ulation; const tance, power V A	of DC drive, inner current loop and outer speed loop asfer functions, modeling of chopper as gain with swi current controller specification and design, speed cont e-phase PWM signals, sinusoidal modulation, space ant V/f control of induction motor. Operation of slip- electronic based rotor side control of slip ring motor, so <b>DVANCED TECHNIQUES</b>	itching delay, plan troller specification vector theory, con- ring induction mo- slip power recover	nt trans on and onvention otor wiry sche	fer fu design nal sj th ex mes. 0	unction. pace v ternal	on, for vector rotor 9
Unit Cont equa contr Gene modu resis Unit	tions and transformed transformed to the transform	of DC drive, inner current loop and outer speed loop isfer functions, modeling of chopper as gain with swi current controller specification and design, speed cont ee-phase PWM signals, sinusoidal modulation, space ant V/f control of induction motor. Operation of slip- electronic based rotor side control of slip ring motor, s <b>DVANCED TECHNIQUES</b> ased control of DC drive, Phase locked loop cont	itching delay, plan troller specification vector theory, con- ring induction mo- slip power recover- trol of DC moto	nt trans on and onventio otor wi ry sche <b>9</b> r, AC/	fer fr design nal sj th ex mes. 0 DC o	unctic n. pace v ternal <b>0</b> drive	on, for vector rotor <b>9</b> using
Unit Cont equa contr Gene modu resis Unit Micr micr	tions and transformed transformed to the transform	of DC drive, inner current loop and outer speed loop asfer functions, modeling of chopper as gain with swi current controller specification and design, speed cont e-phase PWM signals, sinusoidal modulation, space ant V/f control of induction motor. Operation of slip- electronic based rotor side control of slip ring motor, s <b>DVANCED TECHNIQUES</b> ased control of DC drive, Phase locked loop cont Synchronous motor drives, Stepper motor - rating	itching delay, plan troller specification vector theory, con- ring induction mo- slip power recover- trol of DC moto	nt trans on and onventio otor wi ry sche <b>9</b> r, AC/	fer fr design nal sj th ex mes. 0 DC o	unctic n. pace v ternal <b>0</b> drive	on, for vector rotor <b>9</b> using

Text Books:								
1.	G. K. Dubey, "Fundamentals of Electrical Drives", CRC Press, 2002.							
2.	Subrahmanyam, Vedam "Electrical Drives Concepts and Applications", Mc-Graw Hill Publishing, New							
۷.	Delhi, 2016							
3.	S.K.Pillai, "A first course on Electric Drives", Wiley Eastern Ltd., New Delhi, 2016							
Refe	rence Books:							
1.	G. K. Dubey, "Power Semiconductor Controlled Drives", Prentice Hall, 1989.							
2.	W. Leonhard, "Control of Electric Drives", Springer Science & Business Media, 2001.							
3.	Jai P.Agrawal, "Power Electronics Systems - Theory and Design", Pearson Education, Inc., New Delhi,							
5.	2016							

Course Outcomes:								
Upon con	nple	Bloom's Taxonomy Mapped						
CO1	:	Identify the electric drive for the required speed-torque characteristics	L1: Remembering					
CO2	:	Understand the functioning of DC drive using converters	L2: Understanding					
CO3	:	Understand the functioning of AC drive using converters	L2: Understanding					
CO4	:	Analyse the various control schemes for AC and DC drive	L4: Analyzing					
CO5	:	To use microcontroller based system for motor control	L6: Creating					

COURSE ARTICULATION MATRIX															
COs/ POs	PO 1	PO 2	PO 3	PO 4	РО 5	PO 6	PO 7	PO 8	PO 9	PO 10	PO 11	PO 12	PSO 1	PSO 2	PSO 3
CO1	1	1	1	2	1				0	0	0	1	1	2	
CO2	2	2	2	3	2		1		0	0	0	1	1	2	
CO3	2	2	2	3	2		1		0	0	0	1	2	3	
CO4	2	3	3	3	3	1	2	2	0	0	0	3	2	3	2
CO5	1	2	2	3	3		2		0	0	0	3	1	2	2
Avg	1.6	2	2	2.8	2.2	1	1.5	2	0	0	0	1.8	1.4	2.4	2
3/2/1-indicates strength of correlation (3- High, 2-Medium, 1- Low)															