	10D	EC22	MODERN ELECTRICAL DRIVES	 	T	РС				
	IOF	EGZZ	MODERN ELECTRICAL DRIVES	3	-	P C 0 3				
				1 - 1		<u> </u>				
Course Objectives:										
1. 2.		o understand steady state operation and transient dynamics of a motor load system o study and analyze the operation of the converter / chopper fed DC drive, both qualitatively and								
۷.		antitatively	analyze the operation of the converter / chopper red Do drive, both qualita	посту	and					
3.	Τ̈́o	analyze an	d design the current and speed controllers for a closed loop solid state DC							
4.	То	understand	the implementation of control algorithms using microcontrollers and phas	e locl	ced Ic	юр.				
Unit	I	DC MOTO	RS FUNDAMENTALS AND MECHANICAL SYSTEMS		9	+ 0				
			nduced emf, speed-torque relations; Speed control - Armature and field							
			rol - Constant torque and constant horse power operations. Introductio drives. Characteristics of mechanical system - dynamic equations, compo							
			rements of drives characteristics -multi-quadrant operation; Drive elements							
			f motor rating.	, J.						
Unit	11	CONVED.	TER CONTROL		9 .	+ 0				
			ontrol - Fundamental relations; Analysis of series and separately excited	DC	-					
	•	•	three-phase converters - waveforms, performance characteristics.							
disc	ontin	uous arma	ture current operations; Current ripple and its effect on performance;	Ope	ratior	า with				
free	whee	ling diode;	Implementation of braking schemes; Drive employing dual converter.							
Unit	Ш	INTROD	UCTION TO INDUCTION MOTORS		9	+ 0				
Stea	dy s	tate perfor	rmance equations – Rotating magnetic field – torque production, Eq	uivale	ent ci	ircuit–				
Varia	able	voltage, co	onstant frequency operation –Variable frequency operation, constant Vo	olt/Hz	oper	ation.				
Drive	е оре	erating region	ons, variable stator current operation, different braking methods.							
Unit	IV/	FIELDO	RIENTED CONTROL		•					
			I of Induction machines – Theory – DC drive analogy – Direct and Indirect	meth		+				
			Direct torque control of Induction Machines – Torque expression with							
		TC control s	·		S					
Unit	٧	SYNCHRO	ONOUS MOTOR DRIVES		9	+ 0				
		-	cal rotor motor – Equivalent circuits – performance equations of operation			_				
		_	nd braking, self control – Load commutated Synchronous motor driv	es -	Brush	n and				
Brus	hles	s excitation.	•							
			Total (L-	+T)= ₄	15 Pe	riods				
Cou	rse (Outcomes:								
Upo	n cor	mpletion of	this course, the students will be able to:							
CO1	:	Understar	nd selection of drives for industries.							
CO2	:		arious characteristics of series and separately excited DC motor with I three phase converters.							
CO3	:	Explain ab	oout different conventional speed control methods for induction motors.							
CO4			oout direct and indirect methods of field oriented control and direct Torque	Cont	rol sc	heme				
		for Inducti								
COS			the control schemes for synchronous motor drives.							
Text Books:										
1. 2.			ower Semiconductor Controlled Drives ", PH International, New Jersey, 19 ristor D.C Drives ", John Wiley & Sons, New York, 1981.	<u>о</u> у.						
		imal K Bose, "Modern Power Electronics and AC Drives", Pearson Education Asia 2004.								
3.		,	,							

4.	R.Krishnan, "Electric Motor Drives – Modeling, Analysis and Control", Prentice-Hall of India Pvt. Ltd., New Delhi, 2003.							
Reference Books:								
1.	Subharamanyam V. "Electric Drives-Concepts and Applications ", TMH Publi., 1994							
2.	GobalK.Dubey, "Fundamentals of Electrical Drives", Narosal Publishing House, New Delhi,Second Edition ,2009.							
3.	W.Leonhard, "Control of Electrical Drives", Narosa Publishing House, 1992.							
4.	Murphy J.M.D and Turnbull, "Thyristor Control of AC Motors", Pergamon Press, Oxford, 1988							

PO	CO Statement	PO1	PO 2	PO 3	PO4	PO 5	PO 6	PO 7	PO 8	PO 9	PO10	PO1 1
CO1	Understand selection of drives for industries.	1	1	1	1	2	1	2	1	2	1	2
CO2	Analyse various characteristics of series and separately excited DC motor with single and three phase converters.	1	3	3	2	2	1	2	2	1	1	1
CO3	Explain about different conventional speed control methods for induction motors.	1	1	1	2	2	1	1	2	1	1	1
CO4	Explain about direct and indirect methods of field oriented control and direct Torque Control scheme for Induction motor.	1	1	2	2	2	1	2	2	1	1	1
CO5	Formulate the control schemes for synchronous motor drives.	1	2	3	2	3	1	2	2	1	1	1